APPLICATION NO. 10/772,597

INVENTION: Decisioning rules for turbo and convolutional decoding

INVENTORS: Urbain A. von der Embse

Clean version of how the CLAIMS will read

DEC 3 0 2006 PPLICATION NO. 10/772,597

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CLAIMS

WHAT IS CLAIMED IS:

Claim 1. (currently amended) A means for the new turbo decoding a-posteriori probability p(s,s'|y) in equations (13) of the invention disclosure of the decoder trellis states s', s for the received codeword k-1, k conditioned on the received symbol set $y = \{y(1), y(2), \ldots, y(k-1), y(k), \ldots, y(N)\}$ for defining the maximum a-posteriori probability MAP in turbo decoding and which comprises:

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$$\frac{L(d(k))|y| = ln[\sum_{(s,s'|d(k)=+1)} p(s,s'|y|)]}{-ln[\sum_{(s,s'|d(k)=-1)} p(s,s'|y|)]}$$

the ratio of the a-posteriori probability p(s,s'|y) summed over all state transitions $s' \rightarrow s$ corresponding to the transmitted data d(k)=1 to the p(s,s'|y) summed over all state transitions $s' \rightarrow s$ corresponding to the transmitted data d(k)=0,

30 provide a means for using a factorization of the a-posteriori p(s,s'|y) into the product of the a-posteriori probabilities p(s'|y(j<k)), p(s|s',y(k)), p(s|y(j>k))

p(s,s'|y)=p(s|s',y(k))p(s|y(j>k))p(s'|y(j<k)),

provide a means for the using a turbo decoding forward recursion
 equation for evaluating the said a-posteriori probability
 -p(s'|y(j<k)) using said p(s|s',y(k)) as the state
 transition a-</pre>

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$p(s|y(j< k), y(k)) = \sum_{all s'} p(s|s', y(k)) p(s'|y(j< k))$

posteriori probability of the trellis transition path $s' \rightarrow s$ to the new state s at k from the previous state s' at k-1 and given the observed symbol y(k) to update these recursions for the assumed value of d(k) equivalent to the transmitted symbol x(k) which is the modulated symbol corresponding to d(k).

provide a means for the using a turbo decoding backward recursion equation for evaluating the said a-posterior probability p(s|y(j>k)) using said p(s'|s,y(k)) as the state transition a-posteriori probability

 $p(s'|y(j>k-1) = \sum_{all \ s} p(s|y(j>k))p(s'|s,y(k))$

priori probability—of the trellis transition path $s \rightarrow s'$ to the new state s' at k-1 from the previous state s at k and given the—said observed symbol y(k) to update these recursions for the—said assumed value of d(k) equivalent to the—said transmitted symbol x(k) which is the modulated symbol corresponding to—said d(k) and where said p(s'|s,y(k))=p(s|s',y(k)).

30 provide a means for evaluating the natural logarithm of the state -transition a-posteriori probability p(s|s',y(k)) = p(s'|s,y(k)) as a function which is linear in the received symbol y(k)

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ln[p(s|s',y(k)) = Re[y(k)x^*(k)]/\sigma^2 - |x(k)|^2/2\sigma^2 + p(d(k))
         and wherein p is the natural logarithm ln of p, x* is
          the compolex conjugate of x, and ln[o] is the natural
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          logarithm of [o],
    provide a means for evaluating the said natural logarithm of the
          said state transition a-posteriori probability p(s'|s,y(k))
           -=-p(s|s',v(k)) equal to the sum of the new decisioning
                   DX in equations (11),(16) in the invention
          disclosure and the natural logarithm of the a-priori
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          probability p(d(k)) equal to
               ln[p(s|s',y(k))] = ln[p(s'|s,y(k))]
                               = Re[y(k)x*(k)]/\sigma^2+|x(k)|<sup>2</sup>/2\sigma^2+ p(d(k)
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                                 = DX
                DX = Re[v(k)x^{*}(k)]/\sigma^{2} + |x(k)|^{2}/2\sigma^{2} + ln[p(d(k))]
          and which is linear in said received symbol y(k),
          in which ln[(o)] is the natural logarithm of (o) and x*(k)
          is the complex conjugate of x(x) and the new decisioning
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          metric DX is linear in v(k)
     provide a means for the said new state transition probabilities in
              <del>the</del>said —MAP equations <del>to use the said new</del>
          decisioning metric DX in equations (11), (16) in the
          invention disclosure DX = Re[y(k)x*(k)]/\sigma^2 + |x(k)|^2/2\sigma^2
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          linear in y(k) in place of the current use of the maximum
          likelihood decisioning metric DM equal to
                • DM = [-|y(k) - x(k)|^2/2\sigma^2],
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          which is a quadratic function of y(k),
          provide a means for the natural logarithm of the state
               transition probability in the turbo decoding equations
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tobe a linear function of y(k) in place of the current quadratic function of y(k)

- $\frac{1}{2}$ 5 realizes some of the performance improvements demonstrated in FIG. 5,6 using the new decisioning metrics said DX in the invention disclosure and, provide a means for a new a-posterior mathematical paradym whichenables the MAP turbo decoding algorithms to be 10 restructured to allow the natural logarithms of the decisioning metrics to be linear in the detected symbols in place of the current quadratic dependency on the detected symbols provide a means for a said new a-posteriori mathematical paradym 15 framework which enables the said MAP turbo decoding algorithms to be restructured and to determine the intrinsic -information function of the new decisioning as а DX linear in the-said detected symbolsy(k). metrics said
- Claim 2. (currently amended) A-Wherein in claim 1 a means for the said new convolutional decoding in said MAP a-posteriori probability p(s,s'|y) in equations (13) of this invention disclosure, of the decoder trellis states s',s for the received codeword k-1,k conditioned on the received symbol set y (y(1),y(2),...,y(k-1),y(k),...,y(N)) for defining the state transition metrics in the forward and backward recursive equations for convolutional decoding and which comprises:

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provide a means for the new maximum a-posteriori

— probabilityf(x|y) of the transmitted symbol x given
thereceived symbol y to replace the current maximum
likelihood probability f(y|x) used for convolutional
decoding of the received symbol y given the transmitted
symbol x

provide a means for theusing a new maximum a-posteriori principle which maximizes the a-posteriori probability f(x|y) of the transmitted symbol x with respect to the transmitted symbol x given the received symbol y to replace the current maximum likelihood principle which maximizes 5 the likelihood probability fp(y|x) of y given x with respect to the transmitted symbol x for deriving the forward and the backward recursive equations to implement convolutional decoding, and in which f(x|y) is the aposteriori probability of the transmitted symbol x given 10 the observed symbol y and in which f(y|x) is the likelihood funcion which is the probability of the observed symbol y given the transmitted symbol x provide a means for ausing said factorization of the said a-

provide a means for ausing said factorization of the said aposteriori p(s,s'|y) into the product of the said aposteriori probabilities p(s'|y(j< k)), p(s|s',y(k)), p(s|y(j>k)) to identify the convolutional decoding forward state metric $a_{k-1}(s')$, backward state metric $b_k(s)$, and state transition metric $p_k(s|s')$ as the a-posteriori probability factors

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 $\underline{p_k(s|s')} = \underline{p(s|s',y(k))}$ $\underline{b_k(s)} = \underline{p(s|y(j>k))}$ $\underline{a_{k-1}(s')} = \underline{p(s'|y(j<k))}$

provide using a means for the convolutional decoding forward

______recursion_equation for evaluating the said a-posteriori

______probability a_k(s)=p(s|y(j<k),y(k)) using said

p_k(s|s')=p(s|s',y(k)) as the said state transition

probability of the trellis transition path s'→s to the new state s at k from the previous state s' at k-1, and given the observed symbol y(k) to update these recursions for the assumed value of d(k) equivalent to the assumed value for x(k) corresponding to d(k)

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provide a means for theusing a convolutional decoding backward
         -recursion equation for evaluating the said a-posteriori
         probability b_k(s) = p(s|y(j>k))
                                                    using
                                                               said
                                     the—said state transition
                                as
         p_k(s'|s) = p(s'|s,y(k))
         probability of the trellis transition path s >> s' to the new
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         state s' at k-1 from the previous state s at k, and given
         the observed symbol y(k) to update these recursions for the
         assumed value of d(k) equivalent to the assumed value for
         x(k) corresponding to d(k)
    provide a means for evaluating the natural logarithm of the said
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        state transition a-posteriori probabilities ln[p_k(s'|s)] =
        ln[p(s'|s,y(k))] = ln[p(s|s',y(k))] = ln[p_k(s|s')], as a
        - function which is linear in the received symbol y(k) equal
         to said DX and,
         provide a means for evaluating the natural logarithm of the
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         statetransition a-posteriori probabilities
         ln[p(s'|s,y(k))] = ln[p(s|s',y(k))] equal to the sum of the
         new decisioning metric DX in equations (11), (16) in the
         invention disclosure and the natural logarithm of the a-
         priori-probability p(d(k)) equal to
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         ln[p(s'|s,y(k))] = ln[p(s'|s,y(k))]
                   DX = Re \{y(k)x^{*}(k)\}/\sigma^{2} + |x(k)|^{2}/2\sigma^{2}
         in which ln[(o)] is the natural logarithm of (o) and x*(k)
         is the complex conjugate of x(x) and the new decisioning
25
         metric DX is linear in y(k)
         provide a means for the state transition probabilities in
          theconvolutional decoding equations to use the new
         decisioning metric DX-Re[y(k)x*(k)]/\sigma^2+|x(k)|^2/2\sigma^2 in
          equations (11), (16) in the invention disclosure in place
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          of the current use of the maximum likelihood decisioning
          metric equal to \{-|y(k)-x(k)|^2/2\sigma^2-\}
          provide a means for the natural logarithm of the state
          transitionprobability in the convolutional decoding
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equations to be a linear function of y(k) in place of the current quadratic function of y(k)

provide a means for thesaid convolutional decoding algorithms to
 realize some of the performance improvements demonstrated
 in FIG. 5,6 using the new decisioning metrics in thissaid
 invention disclosureDX.

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provide a means for a new a posteriori mathematical paradym
whichenables the convolutional decodingalgorithms
to be restructured to allow the natural logarithms of the
decisioning metrics to be linear in the detected symbols

Claim 3. (currently amended) Wherein in claim 1 A means for the new convolutional decoding recursive equations which calculate said MAP a-posteriori probability p(s,s'|y) — in equations (13) of the invention disclosure of the decoder trellis states s',s for the received codeword k-1,k conditioned on the received symbol set y = {y(1),y(2),...,y(k-1),y(k),...,y(N)} for replacing the current probability p(s,s',y) for turbo decoding and for convolutional decoding when the natural logarithm of the a-priori probability is set equal to zero meaning ln[p(d)]=ln[p(x)]=0 and which comprises:

provide a means for a factorization of the apposterioriprobability p(s,s'|y) into the product of the apposteriori probabilities a_{k-1} , b_k , p_k defined in equations (13) in the invention disclosure

and the natural logarithms are $\underline{a}_{k-1} = \ln[a_{k-1}]$, $\underline{b}_k = \ln[b_k]$, $\underline{p}_k = \ln[p_k]$ and replacing the current factorization of p(s,s',y) into the product of the α_{k-1} , β_k , γ_k in equations (3) in the background art

$$\alpha_{k-1}(s') = p(s', y(j < k))$$

$$\beta_{k}(s) = p(y(j > k) + s)$$

 $\gamma_*(s,s') = p(s,y(k)|s')$ and the natural logarithms are $\underline{\alpha}_{k-1}=\ln{\{\alpha_{k-1}\}}$, $\underline{\beta}_k=\ln{\{\beta_k\}}$, $\gamma_{k}=\ln{\{\gamma_{k}\}}$ provide a means for thesaid forward recursion equation for -evaluating said natural log, a_k , of a_k 5 using $p_k = \ln[p(s|s', y(k))]$ as the natural logarithm of the said state transition a-posteriori probability of the trellis transition path $s' \rightarrow s$ to the new state s at k from the previous state s' at k-1 and given the observed symbol y(k) to update these recursions for the assumed value of d(k) 10 equivalent to the transmitted symbol x(k) which is the modulated-symbol corresponding to d(k) and is $a_k(s) = \max_{s'} [a_{k-1}(s') + p_k(s|s')]$ 15 $= \max_{s'} \frac{[a_{k-1}(s') + DX(s|s')]}{[a_{k-1}(s') + DX(s|s')]}$ = $\max [a_{k-1}(s') + \text{Re}[y(k)x^*(k)]/\sigma^2 - |x(k)|^2/2\sigma^2 + p(d(k))]$ 20 wherein said $DX(s|s')=p_k(s|s')=p_k(s'|s)=DX(s'|s)=DX_is_said$ new decisioning metric, replacing the current forward recursive equation for evaluating the forward recursion equation for α_k using 25 $\gamma_k(s,s') = \ln[p(s,\gamma(k)|s')]$ as the natural logarithm of the state transition probability of the trellis transition path s'->s to the new state s at k from the previous state s' at k-1 and the probability of the observed symbol y(k). provide a means for thsaid e-backward recursion equation for 30 said b_k using said evaluating natural $p_k = \ln[p(s'|s,y(k))] = \ln[p(s|s',y(k))]$ as the logarithm of the said state transition a-posteriori

probability of the trellis transition path $s \rightarrow s'$ to the new state s' at k-1 from the previous state s at k and given the observed symbol y(k) to update these recursions for the assumed value of d(k) equivalent to the transmitted symbol x(k) which is the modulated symbol corresponding to d(k) and is

$$b_{k-1}(s') = \max_{s} [b_k(s) + DX(s'|s)] \text{ and,}$$

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replacing the current forward recursive equation for evaluating the forward recursion equation for β_k using $\gamma_k(s,s') = \ln[p(s,y(k)|s')]$ as the natural logarithm of the state transition probability of the trellis transition path $s' \rightarrow s$ to the new state s at k from the previous state s' at k-1 and the probability of the observed symbol y(k) provide a means for evaluating the natural logarithm of the statetransition—a posteriori—probability—p(s|s',y(k))=

p(s'|s,y(k)) as a function which is linear in the received symbol y(k)

provide a means for evaluating the natural logarithm of the statetransition a-posteriori probability p_k equal to the sum of the new decisioning metric DX in equations (11), (16) in the invention disclosure and the natural logarithm of the a-priori probability p(d(k)) equal to

$$\frac{p_{k} = DX + \ln[p(d(k))]}{DX = Re[y(k)x^{*}(k)]/\sigma^{2} + |x(k)|^{2}/2\sigma^{2}}$$

	$DM = -+y(k)-x(k)+^2/2\sigma^2$
	and our new decisioning metric DX is linearly proportional
	to y(k) and the current decisioning metric DM is a
	quadratic function of y(k)
5	provide a means for the natural logarithm of the state
	transitionprobability in the turbo and convolutional
	decoding equations to be a linear function of y(k) in place
	of the current quadratic function of y(k)
	<pre>provide a means for the said decoding algorithms to realize some</pre>
10	-of_the performance improvements demonstrated in FIG. 5,6
	using the new decisioning metrics in this invention said DX.
	disclosure
	provide a means for a new a posteriori mathematical paradym
	— whichenables the decoding algorithms to berestructured
15	to allow the natural logarithms of the decisioning metrics
	to be linear in the detected symbols

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ABSTRACT OF THE DISCLOSURE

ABSTRACT

The present invention describes new New and improved aposteriori decoding probabilities, decisioning metrics, and implementation algorithms for turbo and convolutional and turbo decoding. Convolutional, decoding algorithms for forward and reverse decoding use a maximum likelihood ML algorithm in a trellis architecture that determines a path metric based on decision metric measurements to find the best trellis path. This ML algorithm can be modified to a maximum a-posteriori MAP iterative algorithm for turbo decoding. Turbo decoding algorithms use the MAP path metrics based on decision metric measurements and a priori probabilities over the observed data set in the form of a likelihood ratio, to implement iterative decoding. This invention replaces to replace the probabilities and decisioning metrics currently used in the maximum likelihood ML and maximum a-posteriori MAP algorithms, with new and improved A-posteriori probabilities p(x)y) replace the current ML probabilities p(y)x) wherein y is the received symbol and x is the transmitted data and the MAP a-posteriori probability p(s',s|y) replaces the current MAP joint probability p(s',s,y) wherein s',s are the trellis decoding states at k-1,k and y is the observed data set y(k), k =1,2,..., N. This yields a-posteriori probabilities and decisioning metrics that reduce the number of arithmetic multiply operations and thereby reduce the computational complexity, to improve decisioning and bit error rate BER performance, and to provide a new mathematical decoding framework. Complexity is the same as current implementations. improve iterative convergence thereby reducing compexity, improve bit error rate BER performance, and provide a new mathematical decoding paradigme. Complexity, iterations required for convergence, and BER tend to be key performance parameters of interest for most applications.